

CIL  
EMU CRITICAL ITEMS LIST

12/24/91 SUPERSEDES 01/02/90

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Date: 12/05/91

ANALYST:

NAME	P/H	FAILURE	CAUSE(S)	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
FAIR/SEPARATOR/ PUMP/MOTOR ASSEMBLY, ITEM 123	2/1R	125FM90: Motor stops or drops in speed.	CAUSE: Excessive bearing wear or contamination resulting in increased bearing drag or seizure; electrical short or open in the windings; electronic failure; binding.	END ITEM: The motor electronics incorporate an underspeed cutout switch will eliminate power to the motor windings if the speed drops below a predetermined limit (See Note 1 under remarks).  GFE INTERFACE: Reduction or loss of CO2 and moisture removal capability. Increase in salt temperature, humidity, and CO2 level. Possible sublimator (Item 1603) freezing.  MISSION: Termination of EVA.	A. Design - The bearings are changed after 750 hours of operation due to limitations of the grease. An underspeed/stall detector monitors the 123 tachometer signal and shuts off the motor by removing both the motor winding power and control logic drive signals when speed is below trip point. The wires are imbedded in epoxy to prevent damage. Semiconductor failure is minimized through the use of high reliability components. Established reliability capacitors (level S) and resistors (level R) are used and are qualified to the requirements of their respective MIL specs and thermal shocked per conditions II of MIL-STD-202 Method 107. The transistors and diodes are qualified to the requirements of MIL-S-19500 and receive the burn-in of JAN28V level parts per the applicable methods. 1038, 1059, 1840 of MIL-S10-730, the electronic components are operating within the power derating requirements of SW427884. The printed circuit boards are fiberglass/epoxy per MIL-P-13949 Type GF or polyimide per MIL-P-13949 Type GI and manufactured per RSFC-STD-154. Parts mounting and soldering is per MSFF-S10-136 and MSFS300.4 (3A-1). The board assemblies are hard mounted to the case to provide a thermal transfer path between the board heat sinks and the case to direct heat away from the electronic components. The board assemblies are also conformal coated per MIL-A-46146 Dow Corning RTV 3140 for environmental protection. All wiring used in the motor is #22759/11 (teflon insulated). Soldering is per MSFS300.4 (3A-1) and wire crimping is per SW427889 (based on NSC SPEC G 1A3). All wires are strain relieved. Electrical connectors are environmentally sealed to prevent damage due to contamination and humidity. The Hall sensors are hermetically sealed to prevent damage due to contamination, humidity and pressure fluctuations.  B. Test - Component Acceptance test - Motor RPM is calibrated and verified during assembly (SV78793 level). The item is performance tested in the EVA and IVA modes. For the various set conditions in the EVA mode, the motor current shall be 2.6 amps max. For the various set conditions in the IVA mode, the motor current shall be 4.7 amps max. The item is tested for max current draw during start up. The max start up current shall be 8 amps within
SV787994-8 (1)					

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CIL  
EMU CRITICAL ITEMS LIST

12/26/91 SUPERSEDES 01/02/90

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ANALYST:

NAME P/N QTY	FAILURE MODE & CAUSES	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
2/1A	125FM10:		<p>the first five seconds of start up, the item is then subjected to a burn in cycle test where it must operate for 24 hours. It is cycled 3 times at 3 hours IVA and 5 hours EVA conditions. RPM is monitored during the test.</p> <p>PDA Test - The item is performance tested in the IVA mode and the PBES mode. For the various set conditions in the IVA mode the motor current shall be 4.5 amps max and in the PBES mode conditions, 4.7 amps maximum. RPM is monitored during the test.</p> <p>Certification Test - The item completed 50,000 hours of operation and 6400 on/off cycles exceeding the 15 year certification requirement by more than a factor of three. The 15 year structural vibration, electrical vibration and design shock was completed 12/84. The following engineering changes have been incorporated and certified since this configuration was certified: 42004-342-35 (change power consumption requirement - more amps), 42006-406 (incorporate Nitronic 60 retaining nut), 42006-426 (fuel cup change to assure a good weld), 42006-B18 (water pump changes 10X inspection in areas susceptible to contamination, mass break edges and deburring operation to class 80R J-EMU-123-810), 42006-934 (change bearing limited life requirements).</p> <p>E. Inspection - start speed is adjusted at electronics build using a fixed resistor in the R153 position on inner board assembly (3U77BB0). An HSD and gov't MP exists to verify proper resistance value is chosen based on testing performed to determine the resistance required to facilitate a start speed of 15,000 +/- 100 RPM. A test is performed to verify proper functioning of the shutdown logic and relay (KC 382) drive transistor. Start speed is verified just after boards are wired together (first performance) just after boards are stacked on housing (second performance) just after electronics cover is assembled (third performance) and at final performance test after all assembly and testing (including vibration) are completed.</p>

SP-001H  
S25  
S26  
S27