

**FAILURE MODES EFFECTS ANALYSIS (FMEA) - NON-CIL HARDWARE
NUMBER: M5-6MR-8027-X**

SUBSYSTEM NAME: ORBITER DOCKING SYSTEM

REVISION: 0 OCT, 1995

	PART NAME VENDOR NAME	PART NUMBER VENDOR NUMBER
LRU	PACU RSC-E	MC#21-0087-0007 33Y.5212.006

PART DATA

EXTENDED DESCRIPTION OF PART UNDER ANALYSIS:

LINE REPLACEABLE UNIT (LRU) PRESSURIZATION ACTUATION CONTROL UNIT (PACU) -
HOOKS MOTORS LOGIC AND POWER CONTROL.

REFERENCE DESIGNATORS: 40V53A1A4
40V53A1A5

QUANTITY OF LIKE ITEMS: 2
(TWO)

FUNCTION:

PROVIDE HOOKS DRIVE MOTOR CONTROL FOR INTERFACE PRESSURIZATION USING
COMMANDS FROM THE DSCU DURING THE AUTOMATIC SEQUENCE OR IN THE MANUAL
CONTROL MODE.

OUTPUT FUNCTIONS:

- 1) PACU-1: PROVIDE POWER TO THE HOOKS #1 MOTORS M6 & M7.
- 2) PACU-1: PROVIDE AUTOMATIC CONTROL FEEDBACK SIGNALS TO DSCU.
- 3) PACU-1: PROVIDE HOOKS POSITION SIGNAL FOR TELEMETRY AND PANEL INDICATION.
- 4) PACU-2: PROVIDE POWER TO THE HOOKS #2 MOTORS M8 & M9.
- 5) PACU-2: PROVIDE AUTOMATIC CONTROL FEEDBACK SIGNALS TO DSCU.
- 6) PACU-2: PROVIDE HOOKS POSITION SIGNAL FOR TELEMETRY AND PANEL INDICATION.

FAILURE MODES EFFECTS ANALYSIS (FMEA) - NON-CIL FAILURE MODE

NUMBER: M5-6MR-B027-02

REVISION# 1 OCT, 1995

SUBSYSTEM NAME: ORBITER DOCKING SYSTEM

LRU: MC621-0087-0007

ITEM NAME: PACU

CRITICALITY OF THIS FAILURE MODE: 1R3

FAILURE MODE:

INADVERTENT ACTIVATION OF ONE OF THREE MOTOR CONTROL SIGNALS FOR A PAIR OF MOTORS.

MISSION PHASE:

OO ON-ORBIT

VEHICLE/PAYLOAD/KIT EFFECTIVITY: 104 ATLANTIS

CAUSE:

MULTIPLE INTERNAL COMPONENT FAILURES

CRITICALITY 1/1 DURING INTACT ABORT ONLY? NO

CRITICALITY 1R2 DURING INTACT ABORT ONLY (AVIONICS ONLY)? NO

REDUNDANCY SCREEN

- A) PASS
- B) N/A
- C) PASS

PASS/FAIL RATIONALE:

- A)
- B) AT LEAST ONE REMAINING PATH DETECTABLE.
- C)

METHOD OF FAULT DETECTION:

NONE.

MASTER MEAS. LIST NUMBERS:

NONE.

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. FAILURE EFFECTS .

(A) SUBSYSTEM:

DEGRADATION OF REDUNDANCY AGAINST INADVERTENT HOOKS MOTOR ACTIVATION.

(B) INTERFACING SUBSYSTEM(S):

NO EFFECT.

(C) MISSION:

NO EFFECT.

(D) CREW, VEHICLE, AND ELEMENT(S):

FIRST FAILURE - NO EFFECT.

(E) FUNCTIONAL CRITICALITY EFFECTS:

FIRST FAILURE (INADVERTENT ACTIVATION OF ONE OF THREE MOTOR CONTROL SIGNALS) - NO EFFECT.

SECOND FAILURE (INADVERTENT ACTIVATION OF SECOND ASSOCIATED MOTOR CONTROL SIGNAL) - INADVERTENT HOOKS CLOSED COMMAND WHICH WOULD TEMPORARILY PRECLUDE HOOKS OPENING. CREW WOULD PERFORM A LOGIC BUS DROP TO RECOVER FUNCTION.

FIFTH FAILURE (ONE PYROBOLT FAILS TO INITIATE) - LOSS OF CAPABILITY TO IMPLEMENT PYROTECHNIC SEPARATION.

DESIGN CRITICALITY (PRIOR TO OPERATIONAL DOWNGRADE, DESCRIBED IN F): N/A

(F) RATIONALE FOR CRITICALITY CATEGORY DOWNGRADE:

NONE. CRITICALITY UNCHANGED. WORKAROUNDS ADD TO REDUNDANCY.

THIRD FAILURE (INABILITY TO DISABLE AFFECTED APDS LOGIC BUS) - LOSS OF CAPABILITY TO RECOVER FUNCTION.

FOURTH FAILURE (INABILITY TO PERFORM IFM TO DRIVE HOOKS OPEN) - ONE OR MORE HOOKS CANNOT BE OPENED.

SIXTH FAILURE (INABILITY TO PERFORM EVA TO REMOVE 96 BOLTS HOLDING DOCKING BASE TO EXTERNAL AIRLOCK) - INABILITY TO SEPARATE ORBITER AND MIR RESULTING IN LOSS OF CREW AND VEHICLE.

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- TIME FRAME -

TIME FROM FAILURE TO CRITICAL EFFECT: DAYS

TIME FROM FAILURE OCCURRENCE TO DETECTION: MINUTES

TIME FROM DETECTION TO COMPLETED CORRECTIVE ACTION: HOURS

TIME REQUIRED TO IMPLEMENT CORRECTIVE ACTION LESS THAN TIME TO EFFECT?
YES

RATIONALE FOR TIME TO CORRECTING ACTION VS TIME TO EFFECT:
CREW WOULD HAVE SUFFICIENT TIME TO PERFORM IFM OR EVA TO REMOVE 96 BOLTS.

HAZARDS REPORT NUMBER(S) : ORBI 401A

HAZARD DESCRIPTION:
INABILITY TO SEPARATE ORBITER AND MIR.

- APPROVALS -

PRODUCT ASSURANCE ENGR

M. NIKOLAYEVA

DESIGN ENGINEER

B. VAKULIN